FFAG's Wonderful World of Nonlinear Longitudinal Dynamics

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Phase space properties of pendula with nonlinear dependence of 'speed' on momentum
– characterized by discontinuous behaviour w.r.t. parameters

- •F0D0 or regular triplet FFAG lattices lead to quadratic $\Delta L(p)$
- gutter acceleration when energy gain/cell exceeds critical value
- Asynchronous acceleration:

- Normal mode: rf commensurate with revolution f @ fixed points Fundamental & harmonics
- Slip mode: rf deviates from revolution frequency @ fixed points Fundamental & harmonics
- Conclusions and outlook







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Phase space of the equations $x'=(1-y^2)$ and $y'=(x^2-1)$

Linear Pendulum Oscillator

Phase space of the equations x'=y and $y'=a.\cos(x)$

Manifold: set of phasespace paths delimited by a separatrix

Rotation: bounded periodic orbits

Libration: unbounded, possibly semi-periodic, orbits

For simple pendulum, libration paths cannot become connected.



Animation: evolution of phase space as strength `a' varies.

Bi-parabolic Oscillator

Topology discontinuous at a = 1

For a < 1 there is a sideways serpentine path
For a > 1 there is a upwards serpentine path
For a = 1 there is a trapping of two counterrotating eddies within a background flow.



GIF Animations @ W3

Phase space of the equations $x'=(1-y^2)$ and $y'=a(x^2-1)$



Animation: evolution of phase space as strength `a' varies.



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Conditions for connection of fixed points by libration paths may be obtained from the hamiltonian; typically critical values of system parameters must be exceeded.



Quadratic Pendulum Oscillator



Phase space of the equations $x'=(1-y^2)$ and $y'=a.\cos(x)$



Animation: evolution of phase space as strength `*a*' varies.

Condition for connection of libration paths: $a \ge 2/3$

Cubic Pendulum Oscillator Phase space of the equations $x'=y(1-b^2y^2)$ and $y'=a.\cos(x)$

Animations: evolution of phase space as strengths a,b' vary.



Quartic Pendulum Oscillator

Phase space of the equations or $x'=y^2(1-b^2y^2)-1$ and $y'=a.\cos(x)$

Animations: evolution of phase space as strengths a,b' vary.



Parameter `*a*` is varied from 0.1 to 2.9 while `*b*` held fixed at b=1/3.



Parameter b^{i} is varied from to 0.1 to 0.5 while a^{i} held fixed at a=3/4.

Equations of motion from cell to cell of accelerator: τ_0 =reference cell-transit duration, τ_s =2 π h/ ω T_n = t_n - $n\tau_s$ is relative time coordinate E_{n+1} = E_n +eV cos(ωT_n) T_{n+1} = T_n + $\Delta T(E_{n+1})$ +(τ_0 - τ_s)

Conventional case: $\omega = \omega(E)$, ΔT is linear, $\tau_0 = \tau_s$, yields synchronous acceleration: the location of the reference particle is locked to the waveform, or moves adiabatically. Other particles perform (usually nonlinear) oscillations about the reference particle.

Scaling FFAG case: ω fixed, ΔT is nonlinear, yields asynchronous acceleration: the reference particle performs a nonlinear oscillation about the crest of the waveform; and other particle move convectively about the reference.Two possible operation modes are normal $\tau_0 = \tau_s$ and slip $\tau_0 \neq \tau_s$ (see later).

Hamiltonian: $H(x,y,a)=y^3/3 - y - a sin(x)$ For each value of x, there are 3 values of y: $y_1 > y_2 > y_3$

We may write values as y(z(x))where $2\sin(z)=3(b+a Sinx)$ $y_1=+2\cos[(z-\pi/2)/3]$, $y_2=-2\sin(z/3)$, $y_3=-2\cos[(z+\pi/2)/3]$.





The 3 libration manifolds are sandwiched between the rotation manifolds (or *vice versa*) and become connected when a≥2/3. Thus energy range and acceptance change abruptly at the critical value.





Phase portraits for 3 through 12 turn acceleration; normal rf





Acceptance and energy range versus voltage for acceleration completed in 4 through 12 turns







Requirements for lattice

The need to match the path-length parabola to the gutter entrance/exit and fixed points of the phase space has implications for $\delta T_1 \& \delta T_2$ etc. Hamiltonian parameter $a = \sigma \times \rho$.

Example: a=2/3 means σ =2, ρ =1/3 and $\delta T_1 / \delta T_2$ =3.

If requirements are violated, then acceptance and acceleration range may deteriorate.



Addition of higher harmonics The waveform may be flattened in the vicinity x=0 by addition of extra Fourier components $n\ge 2$





Restoring force $a \times sin(x) \Rightarrow$ a[n³ sin*x*-sin(n*x*)]/(n³-n)

4 turns a

n

Analogous discontinuous behaviour of phase space, but with revised critical values a_c . Write $\rho = a/a_c$

Asynchronous acceleration with slip rf $\tau_0 \neq \tau_s$

 $T_{n+1} = T_n + \Delta T(E_{n+1}) + (\tau_0 - \tau_s)$

And vary initial cavity phases

E (GeV) 20 18 16 '4 12 -10 8 -0.3-0.2-0.1-0.0 0.1 0.2 0.3 phuse/2n

Phase portrait: 3-5 turn acceln.

There is a turn-to-turn phase jumping that leads to a staggering of the phase traces and a smaller r.m.s. variation of rf phase.



Phase portrait: 6-9 turn acceln.

As the number of turns increases, so does the range and number of the outliers. When a significant portion reach `trough phases' the beam fails to receive sufficient average acceleration – limit about 8 turns f.p.c.

Asynchronous acceleration with slip rf and harmonics



Acceptance and acceleration range vary abruptly with volts/turn. Critical a_c can be estimated by tracking of particle ensemble

Phase spaces for normal rf with harmonics 6-turn 7-turn fundamental +3rd harmonic +2

 8-turn +2nd harmonic



Phase spaces for slip rf with harmonics6-turn
fundamental7-turn
+3rd harmonic

 8-turn +2nd harmonic



Conclusions at the time of:

"Methodical, Insidious Progress on Linear Non-scaling
FFAGs using High-frequency (≥100 MHz) RF"
C. Johnstone *et al*NuFact03
Columbia Univ., NY
June 10, 2003

Performace of nonlinear systems, such as quadratic, cubic, quartic pendula, may be understood in terms of libration versus rotation manifolds and criteria for connection of fixed points.

Same criteria when higher harmonics added; critical *a* renormalized.

Normal and slip rf operations produce comparable performance. Acceleration is asynchronous and cross-crest.

The acceptance & acceleration range of both normal and slip rf have fundamental limitations w.r.t. number of turns and energy increment – because gutter paths becomes cut off.

Regime in which slip rf performs best is one in which energy-increment parameter $a \approx 1$; but this also regime in which phase-space paths become more vertical for normal rf operation.

Nonlinear acceleration is viable and will have successful application to rapid acceleration in non-scaling FFAGs.

What would we do different? (October 2003)

Consider different magnet lattices – quadratic dispersion of path length versus momentum may be smaller.

•Reference trajectory for construction of lattice and transverse dynamics is not necessarily the same as that for longitudinal dynamics. This allows zeros of path length and/or $\delta T_1/\delta T_2$ to be adjusted.

Pay more careful attention of matching longitudinal phase space topology to desired input/output particle beam. Perhaps adjust $\delta T_1/\delta T_2$ as function of a.

Match orientation and size of beam to the libration manifold. For example, if inject/extract at $x = \pm \pi/2$, $\sigma = 2 \cosh[(1/3) \operatorname{arccosh}(a/a_c)], \rho = -1 + \sigma^2/3$

If FOD0 or regular triplet, dispersion of arrival times (at extraction) is a symmetric minimum about central trajectory H(x,y,a)=0; inject beam on to that trajectory.